

An Internet of Thing based Agribot (IOT-Agribot) for Precision Agriculture and Farm Monitoring

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Abstract: Developing nations like India have a huge potential for agricultural business and better cultivation. Because of the large size of cultivation land, improper water supply systems and lack of technology-based agricultural practices, there is a huge gap among expected and actual quantity and quality of agricultural products. Hence there is a need for significant revival in agribusiness using emerging technologies. The article proposes an intelligent water framework device called Agribot designed for the agricultural industry to minimize the water wastage and a better supply of cultivating materials using the Internet of Things (IoT). Our proposed IOT- Agribot will energize the water framework, improve the cost-effective water usage and reduce the labor force to achieve precision agriculture. The proposed IOT- Agribot has performed well for variable weather conditions, soli type, moisture content and crops.

Index Terms: Agribot, IOT, precision agriculture, sensors

1. Introduction

The economic growth of most of countries has been depended on agriculture-based products, rural development and animal livelihood. The present development of the agriculture industry is internet of agriculture (IOA). IOA is aimed for increase the crop yield and minimizing the work force. In existing systems there are various kinds of Agri-bots have been proposed to achieve precision agriculture. These bots can do various functions like detect the soil moisture content, notifications to the farmers, planting, and pesticides spray. These bots have components like Arduino as the main controller, DC motors, relay, battery, servo motor, spiked wheels with well standard mechanical design to resist the real time conditions. Advancement empowered every possible thing to exchange information for better decisions and high quality of service. The single board PCs and Arduino board with DIY is designed for water framework in cultivating [1]. The water framework system is exceptionally using remote sensors and forward the data to world wide web [2]. Data in the cloud is secured and an organization server can monitor, validate the input control movement [3, 4]. Today's precision agriculture is achieved using the advanced farming technologies like wireless sensor networks, satellite technology, robotic machines/bots for auto control and accurate decision w. r. to the real time conditions, and also forwarding the real time data to cloud servers for data analysis, stock management and accurate future predictions.

2. Literature Survey

In sensor based automated irrigation system with internet of things (IOT) [5] has introduced the dampness of the soil and proposed a system to monitor the moisture levels of soil. In this model, a motor pump on or off state is decided by a threshold level of moisture. Pump operation state is communicated to the farmer through GSM module. The farmer receives a short message service (SMS) about the states of pump operations with the help of microcontroller and GSM module connection to MAX 232. Smart irrigation using IOT [6] has proposed a blend of equipment and programming, the model makes use of Arduino Uno R3 microcontroller. The system works on the basis of soil moisture levels. The system has sensors placed over the field and collects the sensor values transferring the data through ESP8266 WIFI module.

In smart irrigation system based on soil moisture levels using IOT [7] has proposed framework consists of Arduino based controlled irrigation system using ESP8266 WiFi Module using IOT platform. In IoT based smart crop-field monitoring and automation irrigation system [8] is introduced two sensors which are used gather the information as simple

qualities. IC3208 changes these simple qualities to 12-bit values, advanced qualities are offered to Raspberry Pi for information transmission to database using Wi-Fi. Sensors are adjusted and the base wet condition in field is 2.4v taken, voltages limits are fluctuated with different yield field in different seasons. IOT based smart irrigation system [9] has proposed with 2 YL-69 soil dampness sensors alongside LM393 comparator modules were set in various soil conditions for investigation. Sensor YL-69 is comprised of two nodes from figure 5. In solar powered smart irrigation system using the internet of things [10], SSIS notwithstanding a correlative Android App has been modeled. Computerized water system framework model specifically SSIS intended to be a proficient and contrast to manual water system frameworks to minimize the wastage of water. This facilitates are managing water utilization of farming area by occasionally assessing dirt dampness, stickiness and temperature through sensors. In IOT Based smart agriculture monitoring system [11], different sensor units are deployed in the field like temperature, PIR and moisture sensors. Information gathered from those sensors are associated with the microcontroller through RS 232. In a multipurpose agricultural robot, Agribot is expected for rustic purposes expected to confine by farmers not withstanding developing pace and precision in work. This plays basic limits identified with creating for example wrinkling field, planting, covering seeds in the dirt [12]. In agricultural aid to seed cultivation [13], an agribot machine insight is making development towards various fields of structure and advancement. Intelligent robots are chomped in cultivation, it is expected to accept the power over agrarian areas and can be work in different weather conditions to improve the agro-business. In the design and operation of Wi-Fi agribot integrated system, the proposed model involves an agribot which helps to locate the position of the seeds planted. This model uses an Arduino board embedded with ATMEGA 328 microcontroller [14] shown in figure 7.

3. Proposed Advanced IOT based Agribot

In our proposed model, the soil sogginess and temperature are evaluated using sensing devices at the field. Data is sent to the cloud by ESP 8266 Wi-Fi module [15] as shown in Fig. 1.

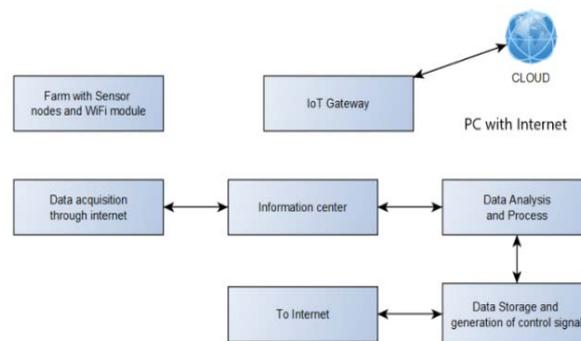


Fig. 1. Proposed IOT-Agribot model

3.1 Design of IOT-Agribot

1. Robot module consists of an Arduino Uno R3 Atmega 328P (5V) board to integrates all functional components.
2. The ultrasonic sensor is used to control the moment of the robot by avoiding the obstacles.
3. The robot stops for every 10 seconds in its journey to collect the values of moisture, temperature, and humidity and updates it to the cloud.
4. Motor drivers L293D are installed to drive the agribot as shown in figure 6.
5. Agribot is controlled using Bluetooth module 8293D.
6. Agribot is powered by solar energy.

3.2 Design Model of Sensor Module

1. All sensing hub consists of sensors, Arduino is utilized to gather sensor information.
2. The soil moisture sensor is used to read the soil moisture values from the crop shown in figure 5.
3. DHT 11 sensor is used to collect temperature and humidity values from the crop.
4. Arduino is utilized to gather sensor information.
5. Wi-Fi availability is given to sensing hub utilizing ESP 8266 module.
6. Arduino sends gathered information to administration servers by means of the Wi-Fi network by IoT portal.
7. The cloud services.

3.3 Pump Operation model

1. The pump operation time is defined based on the moisture contents in the soil as shown in figure 2.
2. If the soil moisture exceeds the threshold value, then the pump motor is to turn off state.
3. If the threshold value is not detected, then threshold values of temperature and humidity are checked and if the

threshold conditions are not reached then the pump operation time is defined and the time is given as delay to the relay and the pump motor is turned off for defined time interval.

4. If the threshold conditions are met, then the system remains in the tuned off state, and the agribot continuously monitors the moisture levels throughout the crop field.

5. Graphical representation of incurred results.

3.3 Hardware

Equipment utilized for creating the proposed framework. ESP-8266 is Wi-Fi module used to interface the sensor to cloud shown in figure 4. DHT-11 for mugginess of soil. 12V DC pump utilized for water supply at any location water content falls below the threshold point as shown figure 3.

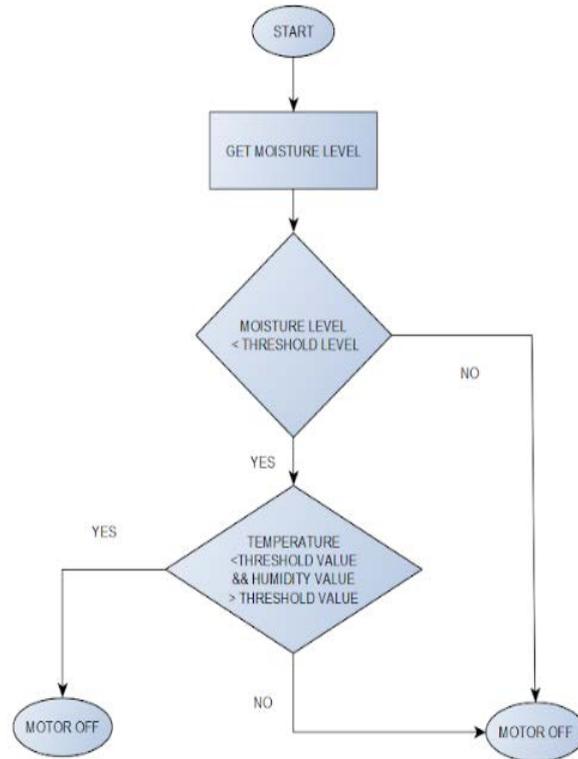


Fig. 2. Water pump operation model using IOT-Agribot

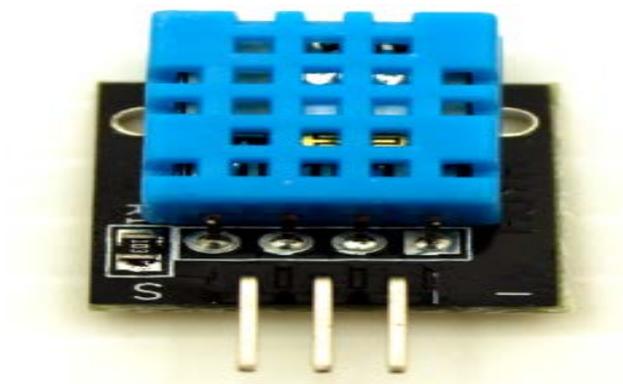


Fig. 3. DHT 11 Temperature and Humidity Sensor of IOT-Agribot

4. Results and Analysis

The developed system is a fully automated agriculture system for efficient resource management, and solar-powered robot harnesses solar energy instead of fuel-based irrigation as shown in figures 8 and 9.

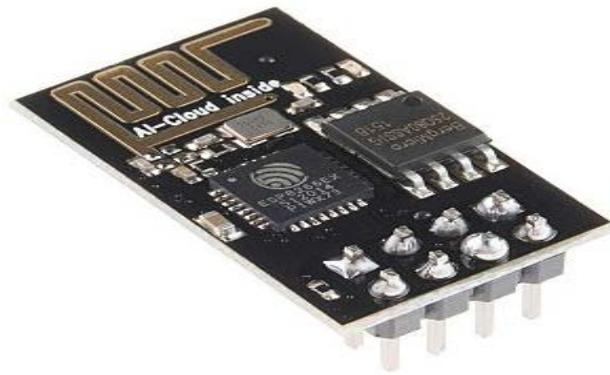


Fig. 4. ESP8266 WIFI module of IOT-Agribot

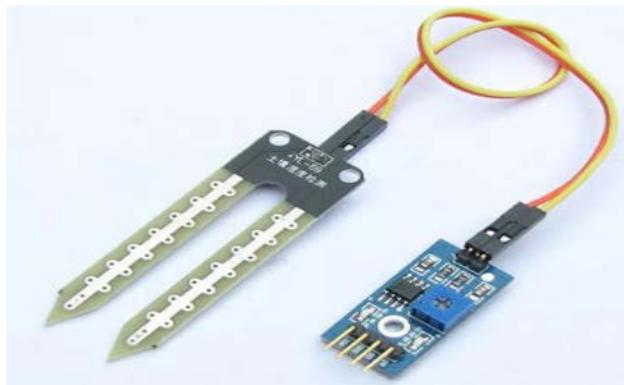


Fig. 5. Soil moisture sensor of IOT-Agribot

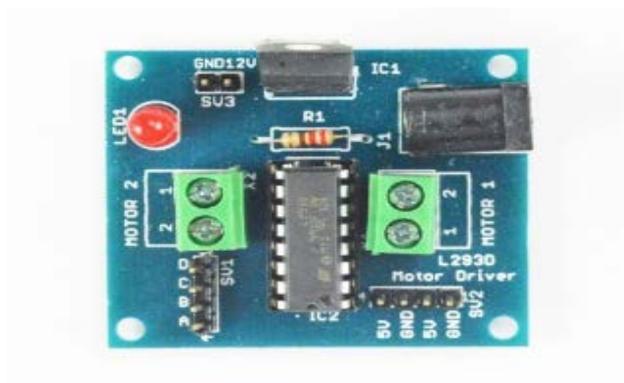


Fig. 6. L293D Motor driver of IOT-Agribot

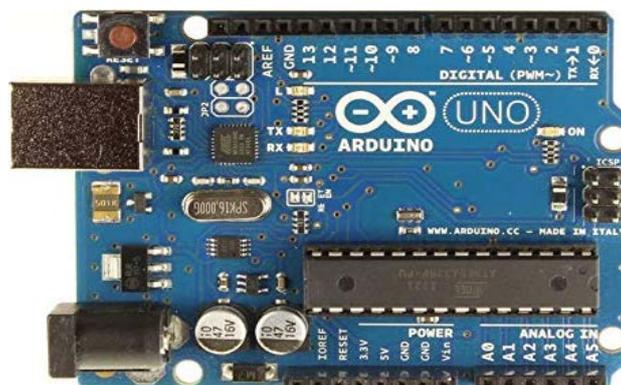


Fig. 7. Arduino UNO R3 microcontroller of IOT-Agribot

The robot module consists of various components including the two-arm robot, Arduino board, ultrasonic sensor, solar panel, relay circuit, and a Bluetooth module. Arduino microcontroller is used as a prime controller to make the entire functioning of the robot possible. The robot is a two-way controlled: automatic and Bluetooth controlled. An ultrasonic sensor is placed at the head of the robot to sense the obstacles. The sensor module is the main hub of the Agribot. This model consists of an Arduino board integrated with a number of sensors includes soil moisture sensor, DHT11 (temperature and humidity sensor), gas sensor, and a motor.

The sensors are continuously collecting the data and update the readings to the cloud. The predefined threshold value for the soil moisture according to the crop and the type of farmland. Whenever the soil moisture is less than the threshold, the pump operation time required for setting the moisture levels to the threshold is displayed at the console. The motor turns on automatically for the said amount of time without human intervention. The sensor module from the equation 1 supplies a sufficient amount of water automatically without manpower. The equation 1 for the pump operation time (POT) is set as follows with threshold value (TV), soil moisture value (SMV) and motor pump rate (MPR).

$$POT = (TV - SMV)/MPR \tag{1}$$



Fig 8. Deployment of IOT-Agribot for real time data collection

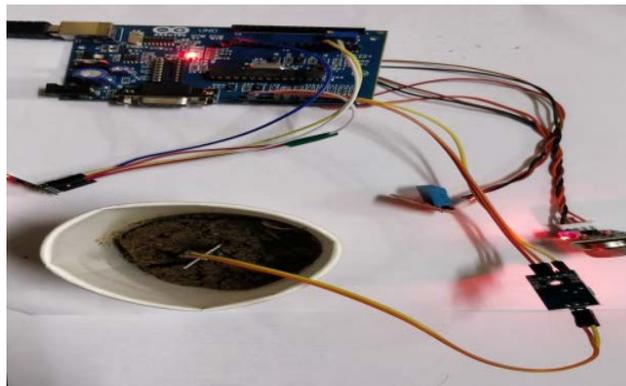


Fig.9. IOT-Agribot Sensor module consists of gas, DHT, moisture

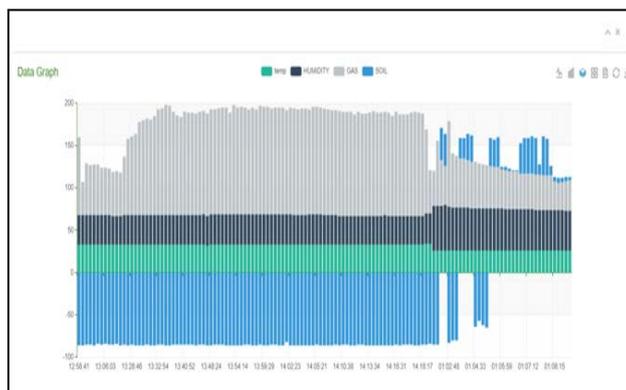


Fig. 10. Gas, Humidity, and Temperature values from Agribot to Cloud Server

The results are including the pump operation time based on moisture, humidity levels in graphical representation. The raw data is continuously updated to the cloud and can be used for further analysis from figures 10 and 11. The raw data at

the cloud server is represented in the form of graphs. The graphs were plotted between time on the x-axis against the soil moisture, temperature, humidity and gas values on the y-axis. In the given case, the soil moisture is far less than the threshold value. The pump rate is calculated accordingly, and the motor turns on based on the estimated time. The estimated time is given as delay to the agribot. In the second case, the soil moisture is less than the threshold value. The pump rate is calculated to turn on the motor based on the estimated time. The estimated time is given as delay to the agribot and the values will be updated in the cloud.

In the third case, the soil moisture is greater than the predefined threshold value. Hence, the pump does not turn on, and the same is displayed on the console. The agribot move on to the field until the next stop. The data will be updated to the cloud. Table 1 shows the results (raw data) received on April 2nd 2019 from 12.58 pm to 02.30 pm from the proposed IOT agribot system and same have been observed in figure 11.

Table 1. The raw data results received from IOT agribot

S. No	temp (C)	humid ity (%)	gas (pc)	soil moist	Time (pm)
1	33	70	92	86.19	12.58
2	33	70	31	86.26	1.04
3	33	70	69	86.22	1.04
4	33	70	59	86.54	1.04
5	33	70	60	86.37	1.04
6	33	70	60	84.11	1.05
7	33	70	56	86.59	1.07
8	33	70	56	84.73	1.12
9	33	70	55	84.55	1.15
10	33	68	52	84.75	1.18
11	33	68	53	84.63	1.21
12	33	68	51	84.52	1.22
13	33	70	69	84.40	1.25
14	33	70	90	84.28	1.32
15	33	70	93	84.17	1.45
16	33	70	96	84.05	1.53
17	33	70	110	83.93	2.00
18	33	70	112	83.82	2.03
19	33	70	114	83.70	2.07
20	33	70	113	83.58	2.10
21	33	70	117	83.47	2.15
22	33	70	125	83.35	2.22
23	33	70	126	83.23	2.30



Fig. 11. IOT-Agribot Console after data analysis

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